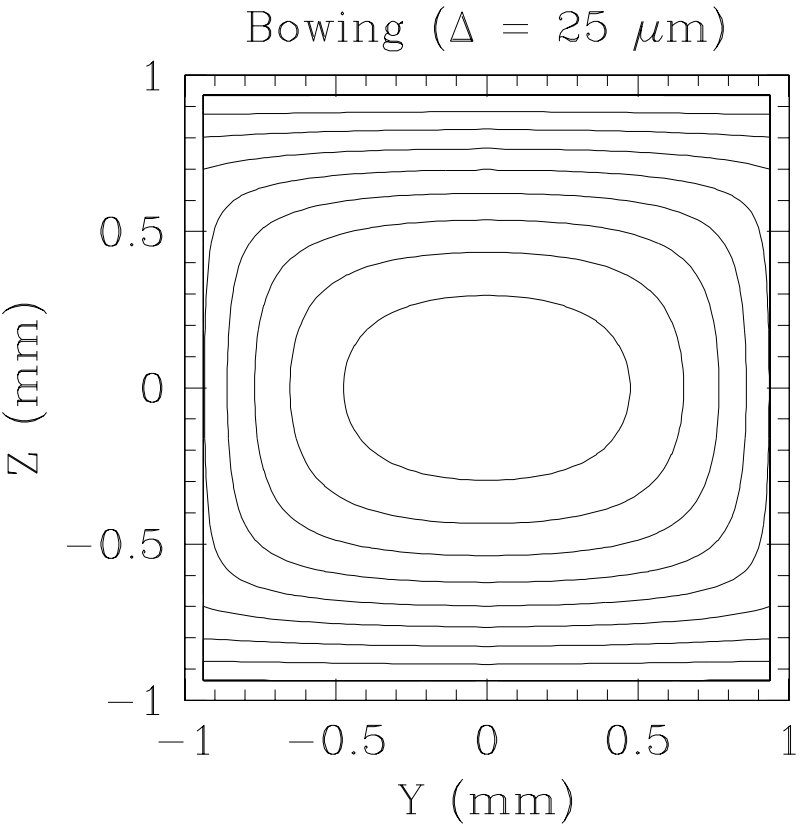
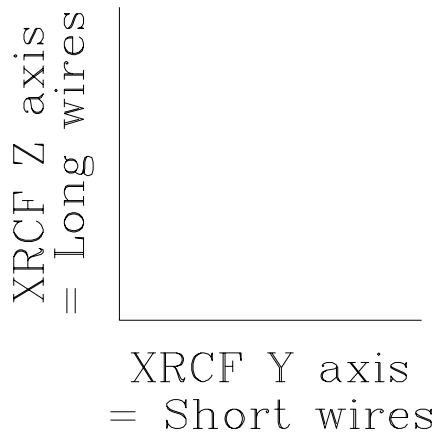
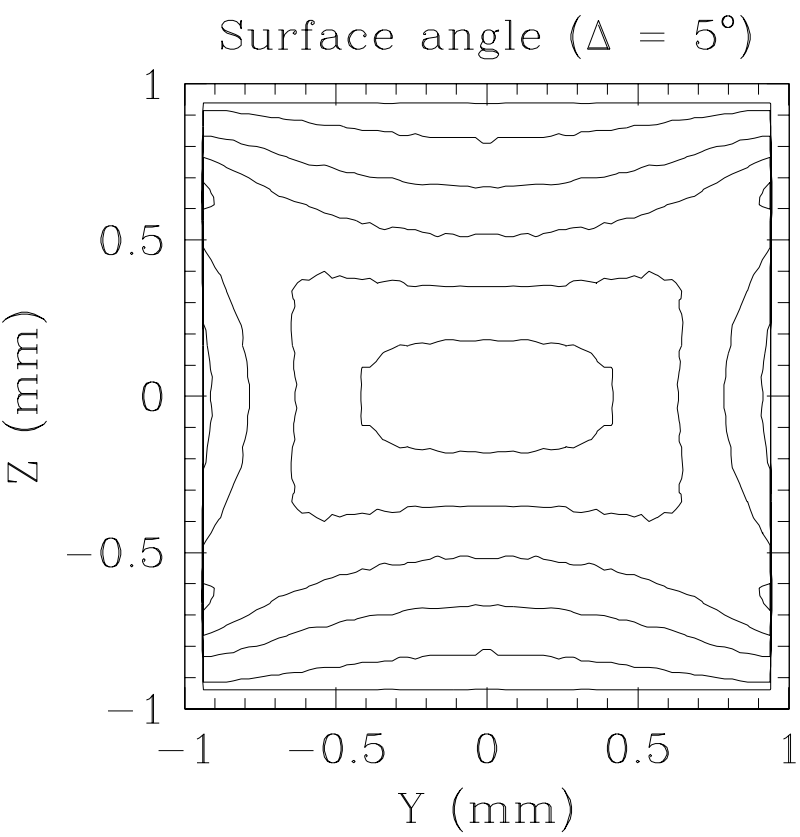
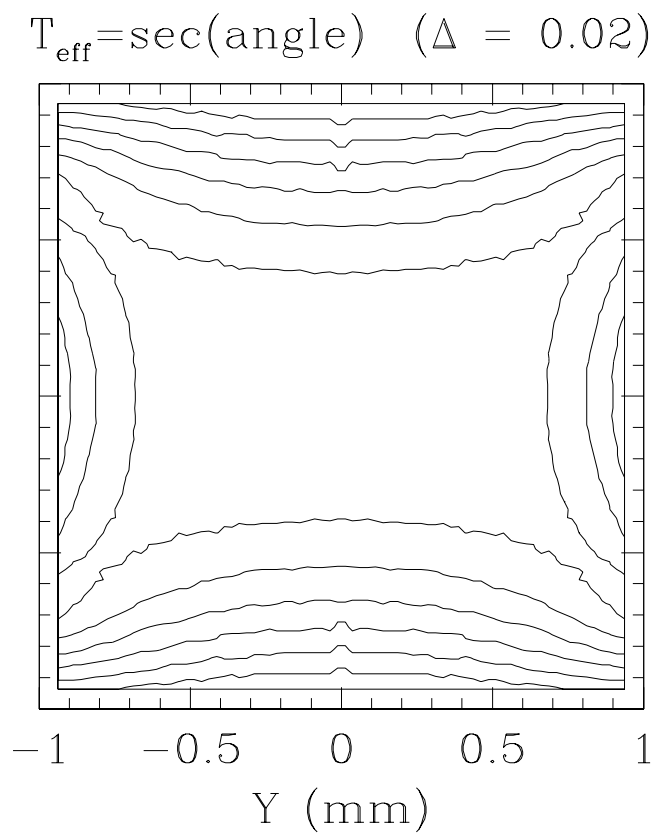

Bowing (Δ = 25 μm)
1
0.5
0
−0.5
−1
Z (mm)
−1
−0.5
0
0.5
1
Y (mm)


XRCF Z axis
= Long wires
XRCF Y axis
= Short wires


Surface angle (Δ = 5°)
1
0.5
0
−0.5
−1
Z (mm)
−1
−0.5
0
0.5
1
Y (mm)


T_eff=sec(angle) (Δ = 0.02)
−1
−0.5
0
0.5
1
Y (mm)